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# Building profile reconstruction using TerraSAR-X data time-series and tomographic techniques

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**MultiTemp 2015**  
**8th International Workshop on the Analysis**  
**of Multitemporal Remote Sensing Images**  
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- Aim of the work
- Urban area: layover
- TomoSAR: main principles
- Dataset

## 2 Interferometric products

## 3 3-D reconstruction

- 3-D height model
- 3-D reflectivity

## 4 Temporal analysis

- 2-D temporal stability
- 3-D temporal stability

## 5 Conclusions

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# Aim of the work

## Why?

- ↗ Necessity to monitor and characterize **Earth's surface dynamics**
- ↗ Interest on **multitemporal data** analysis and processing
- ↗ Number of satellites with **high** spatial and temporal **resolution**

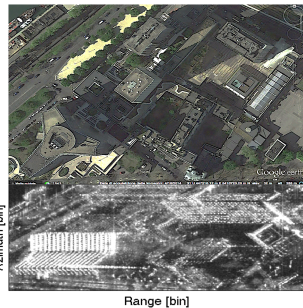
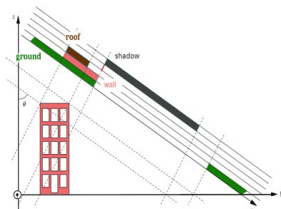
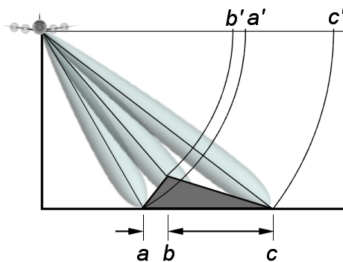
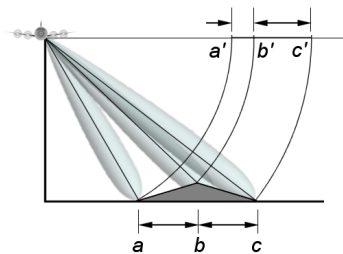
## What?

**3-D** characterization (height, reflectivity, time stability) of **built-up areas**

## How?

- ▷ **SAR Tomography** classical estimators vs. **Compressive Sensing**: temporal analysis and focusing with smaller number of images
- ▷ **TerraSAR-X** data: multibaseline and multitemporal single-pol high resolution Spotlight stack

# Layover elevation displacement

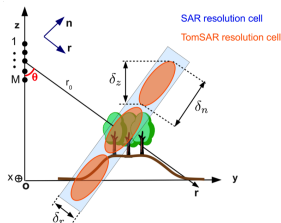
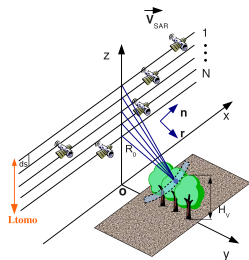


# Tomographic approach

## Tomography SAR principles

- SAR principle in elevation direction (**synthetic vertical aperture**:  $L_{tomo}$ )
- **Multiple passes** of the radar and **resolving ambiguities in elevation**
- **Phase+amplitude** signal information
- **Spectral analysis**: backscattered energy distribution at different heights
- **Good geometric resolution** : high details in the elevation direction

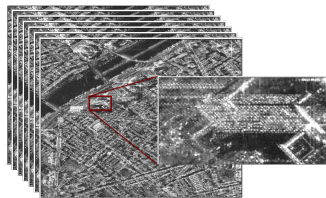
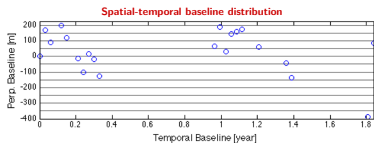
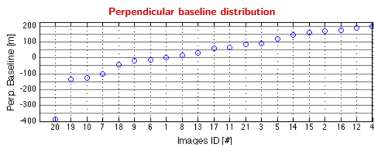
$$\delta_z = \delta_n \sin\theta \text{ with } \delta_n = \frac{\lambda}{R_0} 2L_{tomo}$$



# Test site

- 21 TerraSAR-X\* High Resolution Spotlight (HS) single-pol (HH) images acquired on Paris urban area

\*Acknowledgement to DLR in the frame of the project ID LAN1746



Area Of Interest: multitemporal averaged amplitude (top)

and Google Map (bottom) images



## Stack main characteristics

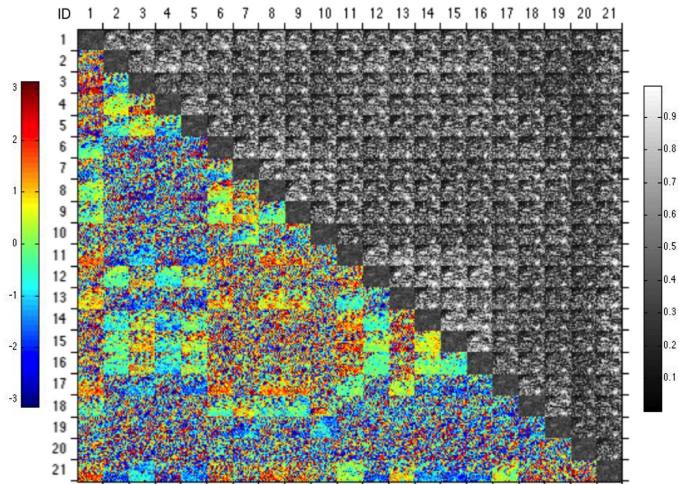
AOI	Acquisition date	Mean look angle (deg)	Orbit	Polarisation	Normal Baseline (m)	Temporal Baseline (days)
Paris	from 24/01/2009	34.7	Asc	HH	Max abs 386.70	Max 506
					Min abs 13.38	Min 11
	to 26/11/2010				Mean abs 116.57	Mean 241.39

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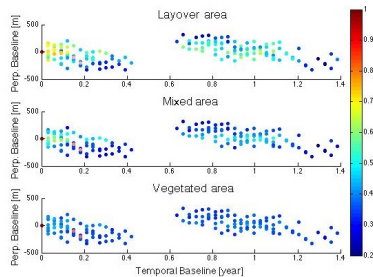
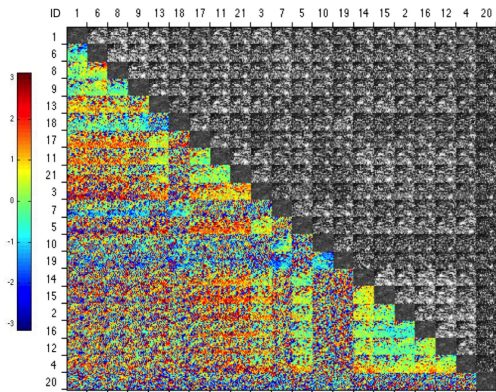
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# Interferogram-coherence matrix: increasing temporal baseline



# Interferogram-coherence matrix: increasing (abs) spatial baseline



Spatial-temporal trend of coherence mean values

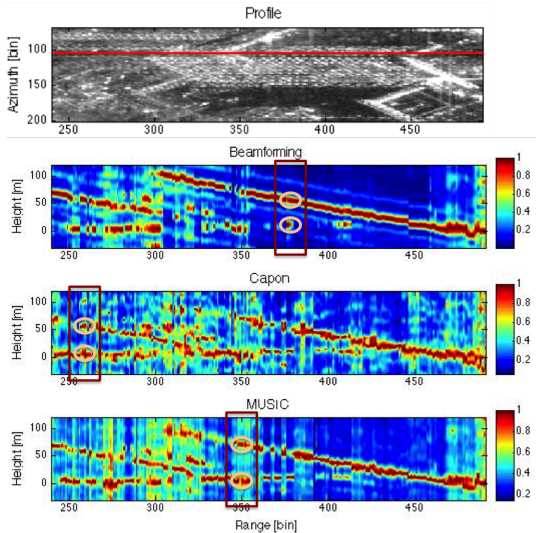
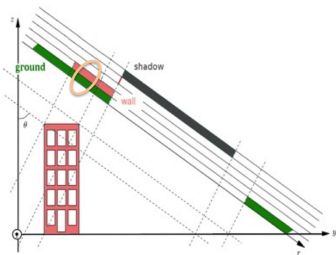
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## 3-D height model

## Slant range tomograms

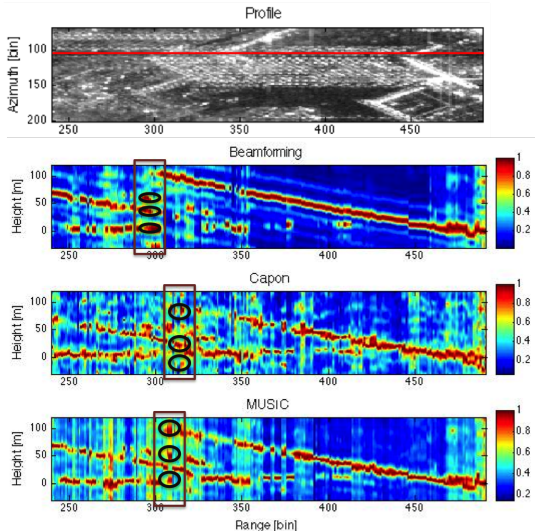
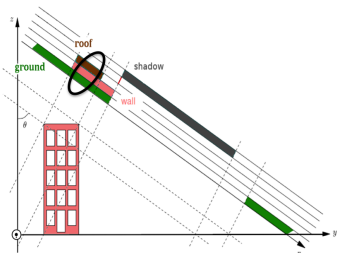
## ■ Layovered profile over AOI



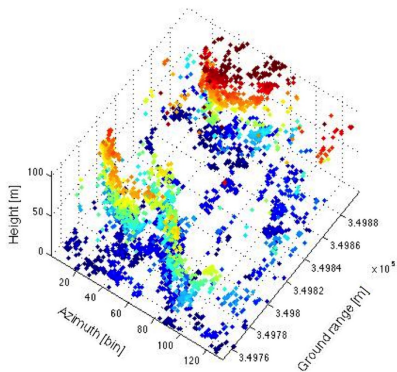
## 3-D height model

# Slant range tomograms

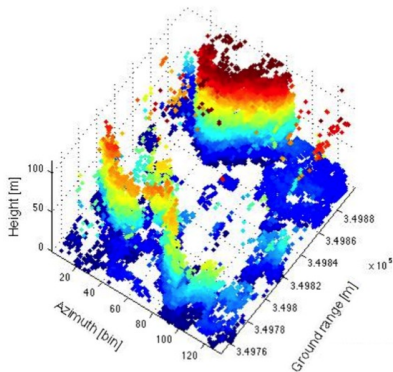
## ■ Layovered profile over AOI



# 3-D elevation map



**MUSIC: second detected scatterers**

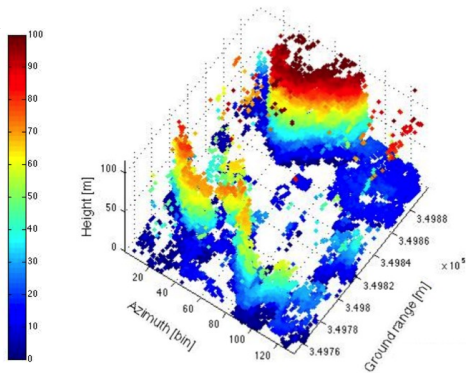


**MUSIC: dominant, second and third detected scatterers**

# 3-D elevation map

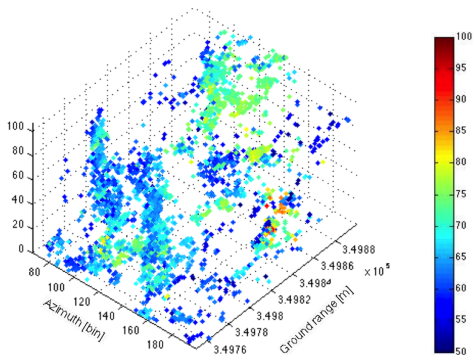


**AOI: Google Earth 3-D view**

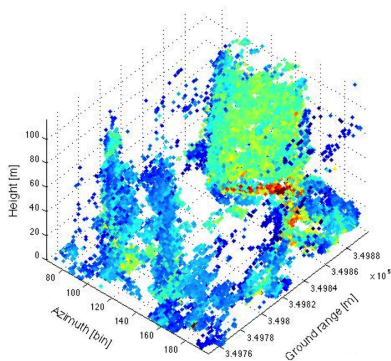


**MUSIC: dominant, second and third detected scatterers**

## 3-D intensity map



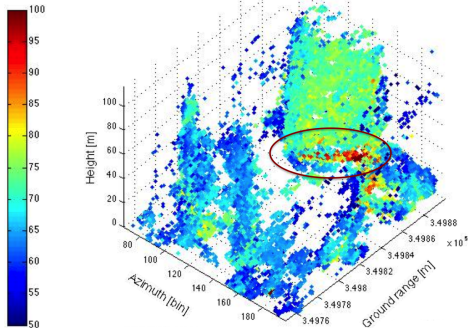
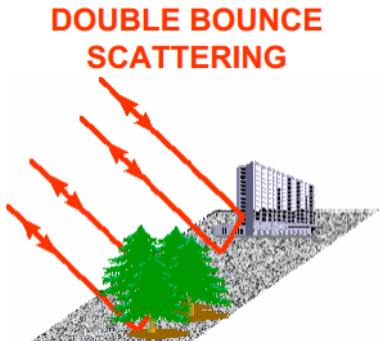
**MUSIC: second detected scatterers**



**MUSIC: dominant, second and third detected scatterers**



## 3-D intensity map



**MUSIC: dominant, second and third detected scatterers**

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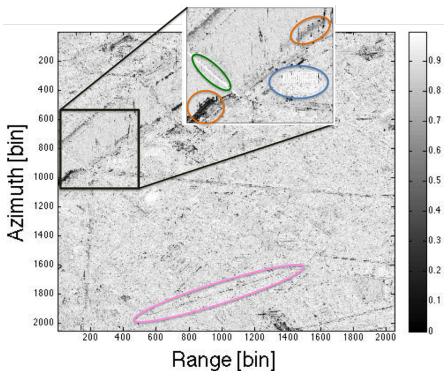
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# Stationarity parameter $\Lambda$

- 2-D temporal (incoherent) stability of

$$\{I_i(x, y)\}_{j=1, j \neq i}^{19}$$

- Maximum Likelihood statistical test

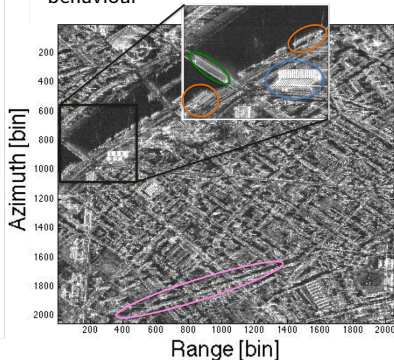


Stationarity parameter  $\Lambda^{(1)}$  on the test site

(1) L. Ferro-Famil and E. Pottier, "Urban area remote sensing from L-band PolSAR data using time-frequency techniques," Urban Remote Sensing Joint Event, URS, 2007

- Buildings, bridges: high stationary behaviour

- Boats, main streets: very low stationary behaviour



Multitemporal averaged amplitude image

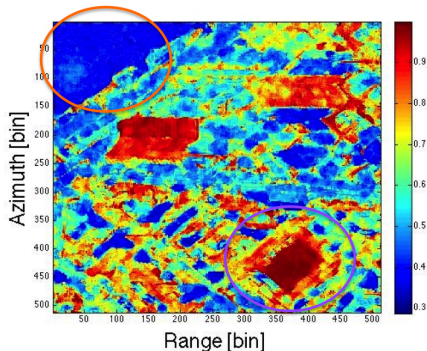
## 2-D temporal stability

Coherence indicator  $\rho$ 

- 2-D temporal (coherent) stability of

$$\{S_j\}_{j=1, j \neq i}^{19}$$

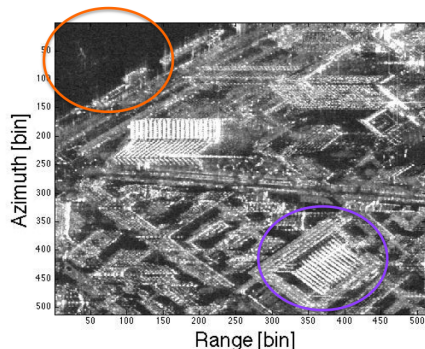
- Maximum Likelihood statistic test



Coherence indicator  $\rho^{(2)}$  over a subset

(2) C. Hu, L. Ferro-Famil, and G. Kuang, "Ship discrimination using polarimetric SAR data and coherent time-frequency analysis," Remote Sensing, vol. 5, no. 12, pp. 6899–6920, 2013

- Man-made targets, **buildings**: very high cross-correlation
- Natural environments**: very low cross-correlation



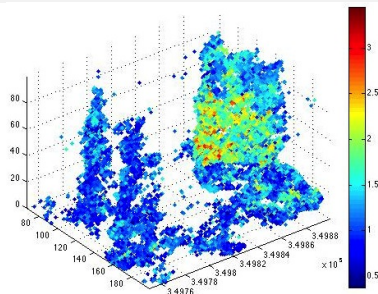
Multitemporal averaged amplitude image

# Temporal stability analysis I

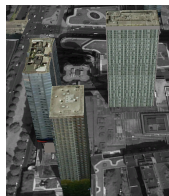
$$\begin{array}{ccc} \{s_j\}_{j=1, j \neq i}^{19} & & 2\text{-D} \\ \Downarrow & \text{TomoSAR} & \Downarrow \\ \{I_i(x, y, z)\}_{j=1, j \neq i}^{19} & & 3\text{-D} \end{array}$$

3-D temporal stability in term of a modified **CV** from **incomplete tomograms**

$$\{I_i(x, y, z)\}_{i=1}^{19}$$



3-D reconstruction of the estimated CV

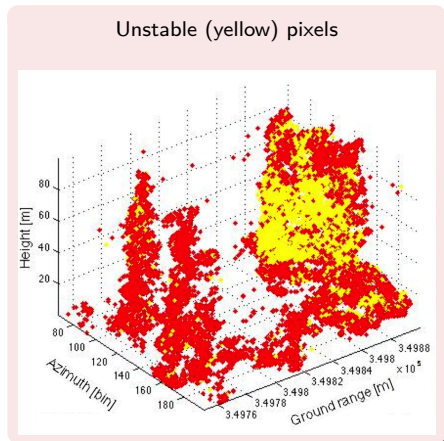


# Temporal stability analysis I

$$\begin{array}{ccc}
 \{s_j\}_{j=1, j \neq i}^{19} & \text{TomoSAR} & \text{2-D} \\
 \Downarrow & & \Downarrow \\
 \{I_i(x, y, z)\}_{j=1, j \neq i}^{19} & & \text{3-D}
 \end{array}$$

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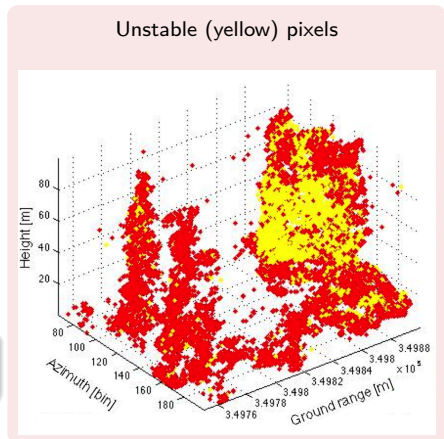
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$$\begin{array}{ccc} \{s_j\}_{j=1, j \neq i}^{19} & \text{TomoSAR} & \text{2-D} \\ \Downarrow & & \Downarrow \\ \{I_i(x, y, z)\}_{j=1, j \neq i}^{19} & & \text{3-D} \end{array}$$

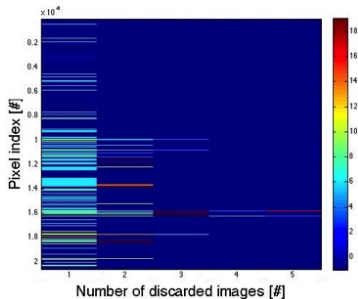
3-D temporal stability in term of a modified **CV** from **incomplete tomograms**

$$\{I_i(x, y, z)\}_{i=1}^{19}$$

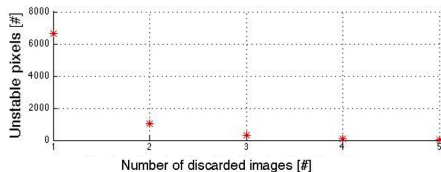
Similar resolution properties and importance of the missing image



## Temporal stability analysis II

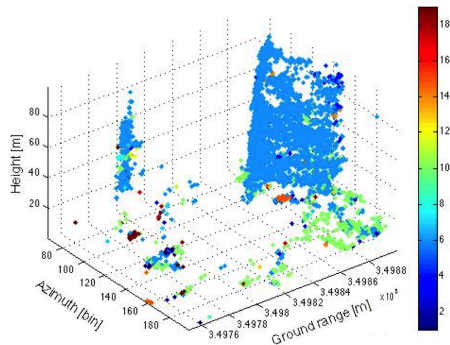


Extraction of the most perturbing contributions



Number of the unstable pixels at different steps

Extraction of the most perturbing contributions



3-D reconstruction of the relative indices at the first step



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# Conclusions

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- Strong **geometric distortions** derived from **layover** in **urban areas** analysis
- Global characterization of **build-up areas**
- **3-D reconstructions** regarding buildings **heights**, vertical **reflectivity** and time **stability** analysis
- **TomoSAR** technique **potentialities**:
  - layover distortions correction
  - separating different scatterers and detecting the corresponding reflectivity within one resolution cell
  - using classical mono-dimensional estimators (not Compressive Sensing)

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*... thank you for your attention!*